

# Correction Examen - M.D.F. Approfondi

Exo 1:

1) En appliquant le principe fondamental de la dynamique:  $F + P_{atm} S_1 = P_1 S_1$  (0,5)

$$\Rightarrow P_1 = \frac{4F}{\pi d_1^2} + P_{atm} \quad (0,5)$$

$$= \frac{4 \times 62,84}{\pi \cdot 0,04^2} + 10^5 = 1,5 \text{ bar} \quad (0,5)$$

2)  $V_1 S_1 = V_2 S_2$  (0,5)  $\Rightarrow V_1 = V_2 \frac{S_2}{S_1} = V_2 \left(\frac{d_2}{d_1}\right)^2 = \left(\frac{1}{4}\right)^2 V_2$  (0,5)

$$\Rightarrow V_1 = \frac{V_2}{16} \quad (0,5)$$

3)  $\frac{V_2^2 - V_1^2}{2} + \frac{P_2 - P_1}{\rho} + g(z_2 - z_1) = 0$  (0,5)

$$\begin{cases} z_1 = z_2 \\ P_2 = P_{atm} \end{cases} \Rightarrow V_2 = \sqrt{\frac{512}{255} \frac{P_1 - P_{atm}}{\rho}} \quad (0,5)$$

AN:  $V_2 = \sqrt{\frac{512}{255} \frac{(1,5 \cdot 10^5 - 10^5)}{1000}} = 10 \text{ m/s}$  (0,5)

4)  $q_v = \frac{\pi d_c^2}{4} V_2 = \frac{\pi \cdot 0,01^2}{4} \times 10 = 0,785 \cdot 10^{-3} \text{ m}^3/\text{s}$  (0,5)

## Ex 2

$$1) \frac{u(y)}{U} = \frac{y}{\delta(x)}$$

$$\delta_2 = \int_0^{\delta} \frac{u}{U} \left(1 - \frac{u}{U}\right) dy = \int_0^{\delta} \frac{y}{\delta} \left(1 - \frac{y}{\delta}\right) dy = \frac{\delta(x)}{6} \quad (0,5)$$

$$\tau_w = \mu \frac{\partial u}{\partial y} \Big|_{y=0} = \mu \frac{U}{\delta(x)} = \rho U^2 \frac{d\delta_2}{dx} = \frac{1}{6} \rho U^2 \frac{d\delta(x)}{dx} \quad (0,5)$$

$$\Rightarrow \delta(x) d\delta(x) = \frac{6\nu}{U} dx$$

$$\Rightarrow \int_0^{\delta} \delta(x) d\delta(x) = \int_0^x \frac{6\nu}{U} dx \Rightarrow \frac{\delta^2(x)}{2} = \frac{6\nu}{U} x \quad (0,5)$$

$$\Rightarrow \frac{\delta(x)}{x} = \frac{3,46}{\sqrt{Re_x}} \quad (0,8)$$

$$2) \tau_w = \mu \frac{\partial u}{\partial y} \Big|_{y=0} = \mu \frac{U}{\delta} \quad (0,5)$$

$$C_f = \frac{\tau_w}{\frac{1}{2} \rho U^2} = \frac{\mu \frac{U}{\delta}}{\frac{1}{2} \rho U^2} = \frac{2\mu}{\rho U \frac{3,46x}{\sqrt{Re_x}}} \Rightarrow C_f = \frac{0,571}{\sqrt{Re_x}} \quad (0,5)$$